

A simple model for  
**Coarsening in Infinite Particle Systems**

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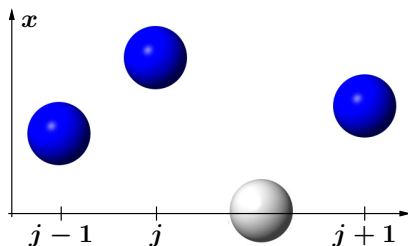
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## A simple model

Particles  $x_j > 0$ ,  $j \in \mathbb{Z}$  governed by

$$\dot{x}_j = x_{j+1}^{-\beta} - 2x_j^{-\beta} + x_{j-1}^{-\beta} = \text{“}\Delta(x_j^{-\beta})\text{”}$$

where vanished particles  $x_j = 0$  are removed and the remaining ones are remeshed.



## A simple model

### Applications

Equations of type  $\dot{x}_j = \Delta g(x_j)$  appear e. g. in



Picture: Darren Lewis,  
[www.publicdomainpictures.net](http://www.publicdomainpictures.net)

- convective Cahn-Hilliard (Watson, Otto, Rubinstein, Davis 2003),
- models for sand ripples (Hellén, Krug 2002).

### Mathematical Interest

- toy model for neighbourhood interactions,
- rigorous statistical description (coarsening, self-similarity),
- well-posedness for infinite systems.

## Existence of solutions

### Screening in spatially homogeneous systems

Large particles

$$x_{j_k} \geq d, \quad j_{k+1} - j_k \leq L,$$

where  $d, L = \text{const} > 0$ ,

- remain large, say  $\geq d/2$ , up to some time  $T_d^*$  due to  $\dot{x}_{j_k} \geq -2x_{j_k}^{-\beta}$ ,
- trap mass  $M_{k,l}(t) = \sum_{j=k}^l x_j(t)$  since

$$\begin{aligned} M_{j_k, j_l}(t) &\geq M_{j_k, j_l}(0) - C_d t, \\ M_{j_k+1, j_l-1}(t) &\leq M_{j_k+1, j_l-1}(0) + C_d t. \end{aligned}$$

## Existence of solutions

### Screening in spatially homogenous systems

→ Homogeneity

$$\frac{1}{L} M_{j_k, j_{k+1}-1}(0) \geq d \quad \text{for all } k \in \mathbb{Z}$$

is preserved up to time  $T_d^*$  in the sense

$$\frac{1}{qL} M_{j_k, j_{k+q}-1}(t) \geq (1 - 1/q)d \quad \text{for all } k, q \in \mathbb{Z}.$$

## Existence of solutions

Global-in-time existence follows from

- truncation  $x^n = (x_{-n}^n, \dots, x_n^n)$ ,
- uniform estimates as  $n \rightarrow \infty$  (depending on  $L, d$ ) and the Arzelà-Ascoli Theorem,
- iteration  $L \rightarrow qL, d \rightarrow (1 - 1/q)d, T_d^* \rightarrow T_d^* + T_{(1-1/q)d}^*$ ,

Solution means

- $x_j$  continuous and  $x_j^{-\beta} \chi_{\{x_j > 0\}}$  locally integrable,
- integral equation

$$x_j(t_2) - x_j(t_1) = \int_{t_1}^{t_2} \Delta_{\sigma(j, x(s))} (x_j(s)^{-\beta}) ds$$

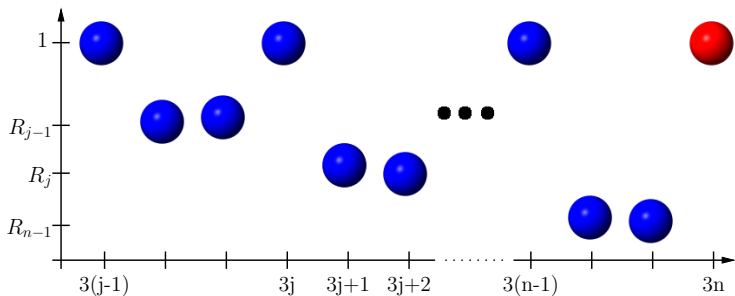
where  $\Delta_{\sigma}$  incorporates neighbourhoods and vanishing.

## Non-uniqueness

### Initial data

$$x_{3j}(0) = 1, \quad x_{3j+1}(0) \approx x_{3j+2}(0) \approx R_j$$

for  $j = 1, 2, \dots, n-1$  where  $(R_j)$  decreases exponentially



and ...

## Non-uniqueness

### Perturbation

$$\begin{aligned} \text{either } x_{3n}(0) &= 1 && \rightarrow && \text{truncated solution } \bar{x}^n \\ \text{or } x_{3n}(0) &= 1 + \varepsilon_n^n && \rightarrow && \text{truncated solution } x^n \end{aligned}$$

is propagated through the solution via

$$\begin{aligned} |\bar{x}_{3(n-1)}^n(T_{n-1}^n) - x_{3(n-1)}^n(T_{n-1}^n)| &= \varepsilon_{n-1}^n > \varepsilon_n^n \\ |\bar{x}_{3(n-2)}^n(T_{n-2}^n) - x_{3(n-2)}^n(T_{n-2}^n)| &= \varepsilon_{n-2}^n > \varepsilon_{n-1}^n \\ &\vdots \end{aligned}$$

and as  $n \rightarrow \infty$  with  $\varepsilon_n^n \rightarrow 0$  yields two different solutions  $\bar{x}$  and  $x$ .

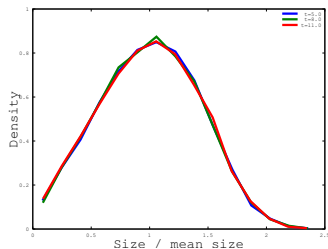
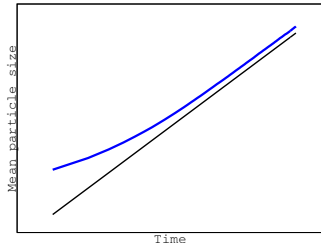


## Coarsening dynamics

Features of coarsening model

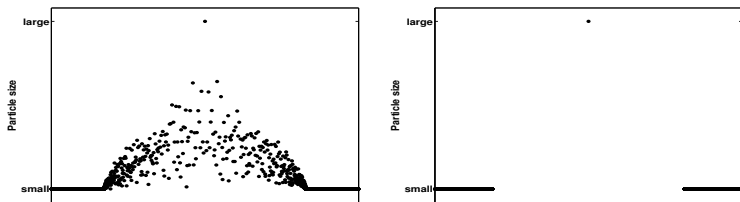
- particles disappear in finite time,
- mass  $\sum x_j$  is (formally or locally) conserved

Generic behaviour in finite systems:  $\langle x \rangle \sim t^{\frac{1}{\beta+1}}$



## Coarsening dynamics in the infinite system

- $\langle x \rangle \lesssim T^{\frac{1}{\beta+1}}$  where  $T$  is the time to transfer a certain amount of average mass from vanishing to surviving particles;
- interesting non-generic behaviour



- explicit solutions with nearly generic coarsening rate by “organized coarsening structures”